# Balanced tree notes

### Prof Bill, Mar 2020

The goal of balanced trees: **O(log n) worst-case performance**. They do this by eliminating the destructive case where a BST turns into a linked list.

Some "textbook" links:

- Morin, 9 Red-black trees, <u>opendatastructures.org/ods-java/9\_Red\_Black\_Trees.html</u>
- Sedgewick algos 3.3 Balanced search trees, <u>algs4.cs.princeton.edu/33balanced</u>

#### Sections:

- 1. Why does balanced = log N?
- 2. B-trees, 2-3-4 trees
- 3. Red-black trees
- 4. AVL trees
- 5. Scapegoat trees

In general, we will learn the rules of each structure, and the insert and search operations. We'll punt on delete. Rationale: Time is limited. If you understand insert and search, then you can figure out delete if you need it.

These notes are just a quick summary of each structure. I'll have separate, detailed Prof Bill notes™ of most/all of these guys.

thanks...yow, bill

# 1. Why does balanced = log N?

Important to understand why this "balanced stuff" works, **O(log n) worst case**.

- Insert and search ops never scour the whole tree, only 1 or 2 branches.
- In a balanced tree, those branches are guaranteed to have log( n) nodes.

Counter-example: Printing the tree (balanced or not) is O(n), each node is visited.

Terms:

- > full binary tree every node that isn't a leaf has two children
- complete binary tree every level except the last is full and all nodes are as far left in the tree as possible

Key: Balanced tree algorithms are O(log n) because their trees are full/complete!



Btw, let's do the maths (for Joe K):

```
# S is num nodes, n is height

# count nodes at each level

S = 2^{0} + 2^{1} + 2^{2} + ... + 2^{(n-1)}

2*S = 2^{1} + 2^{2} + 2^{3} + ... + 2^{(n-1)} + 2^{(n)}

subtract: 2S - S = S

S = -2^{0} + 2^{(n)}

S = 2^{n} - 1
```

### 2. B-trees, 2-3-4 trees

I like Wikipedia here, actually:

- → B-tree, <u>en.wikipedia.org/wiki/B-tree</u>
- → 2-3-4 tree, <u>en.wikipedia.org/wiki/2%E2%80%933%E2%80%934\_tree</u>

B-trees are the general case...nodes with N children.

We will study 2-3-4 trees. These have nodes with 2, 3, or 4 children.



Source: https://en.wikipedia.org/wiki/2%E2%80%933%E2%80%934\_tree

**Insert** new nodes as a leaf, then split nodes that get too large.

**Search** is a little weird, but straightforward.

# 3. Red-black trees

Again. Kudos to Wikipedia, en.wikipedia.org/wiki/Red%E2%80%93black\_tree

The red-black rules are:

- □ Each node is either red or black.
- □ The root is black.
- □ All leaves (NIL) are black.
- □ If a node is red, then both its children are black.
- □ Every path from a given node to any of its descendant NIL nodes contains the same number of black nodes.

Insert a new node as a leaf, then re-color or rotate to maintain our red-black properties.

Search is just like BST...but with the worst-case performance of O(log n).



Source: www.cs.auckland.ac.nz/software/AlgAnim/red\_black.html

#### 4. AVL trees

Wikipedia: en.wikipedia.org/wiki/AVL\_tree

Quickly:

- An AVL tree is a **self-balancing** binary search tree (BST). It was the first such data structure to be invented.
- The AVL tree is named after its two Soviet inventors, Georgy Adelson-Velsky and Evgenii Landis, who published it in their **1962 paper** "An algorithm for the organization of information".
- ➤ The heights of the two child subtrees of any node differ by at most one; if at any time they differ by more than one, rebalancing is done to restore this property.
- Search, insertion, and deletion all take O(log n) time in both the average and worst cases!



/\* AVL is pretty unpleasant to code \*/

# 5. Scapegoat trees

**Read:** Morin 8 Scapegoat trees, <u>opendatastructures.org/ods-java/8\_Scapegoat\_Trees.html</u>

Quick facts: 1) There is no animation for scapegoat trees. 2) I've never used them.

Here's a better explanation than Morin (sigh), brilliant.org/wiki/scapegoat-tree.

• Unlike the red-black tree and the AVL tree, the scapegoat tree is an unencumbered data structure. (no extra info per node, like color)