

# Week 6 Notes

*Prof Bill - Apr 2018*

In Week 6, we'll cover:

A. Binary Trees and BST

B. Priority Queue

thanks... yow, bill

## A. Binary Trees, Binary Search Tree (BST)

\*\* Book: **Muganda 22.1-22.2**

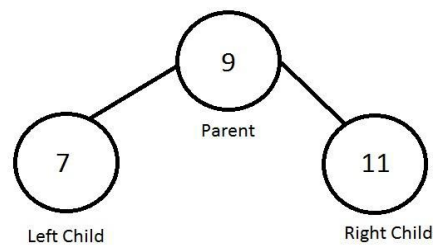
\*\* Online: **Princeton**, [algs4.cs.princeton.edu/32bst](https://algs4.cs.princeton.edu/32bst)

\*\* Online: This **animation** is great: [www.cs.usfca.edu/~galles/visualization/BST.html](http://www.cs.usfca.edu/~galles/visualization/BST.html)

\*\* Online: A nice lecture: [www.cs.cmu.edu/~adamchik/15-121/lectures/Trees/trees.html](http://www.cs.cmu.edu/~adamchik/15-121/lectures/Trees/trees.html)

### 22.1 Binary Trees

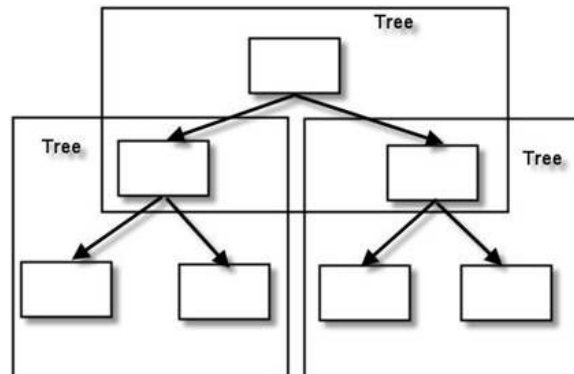
Binary tree has nodes like a linked list. Each **node** has data (key, value) and then left and right node pointers. The **root** is the first node in the tree.



Source: [cppbetterexplained.com/binary-search-trees/](http://cppbetterexplained.com/binary-search-trees/)

Binary trees are recursive structures because nodes have nodes in them.

Also, subtrees behave just like the overall tree. Makes for easy recursive methods.



Binary tree consisting of 3 binary trees

Source: [www.sqa.org.uk/e-learning/LinkedDS04CD/page\\_30.htm](http://www.sqa.org.uk/e-learning/LinkedDS04CD/page_30.htm)

Traversal:

- Preorder: root, left, right
  - Inorder: left, root, right // sorted order in a BST
  - Postorder: left, right, root
- /\* memory helper: 1) root determines pre, in, or post and 2) left always before right \*/

Pseudocode... start process with call: `inorder( root)`:

```
// inorder traversal to print binary tree
void inorder( Node n)
  if n == null then return
  inorder( n.left)
  print n
  inorder( n.right)
```

## 22.2 Binary Search Trees (BST)

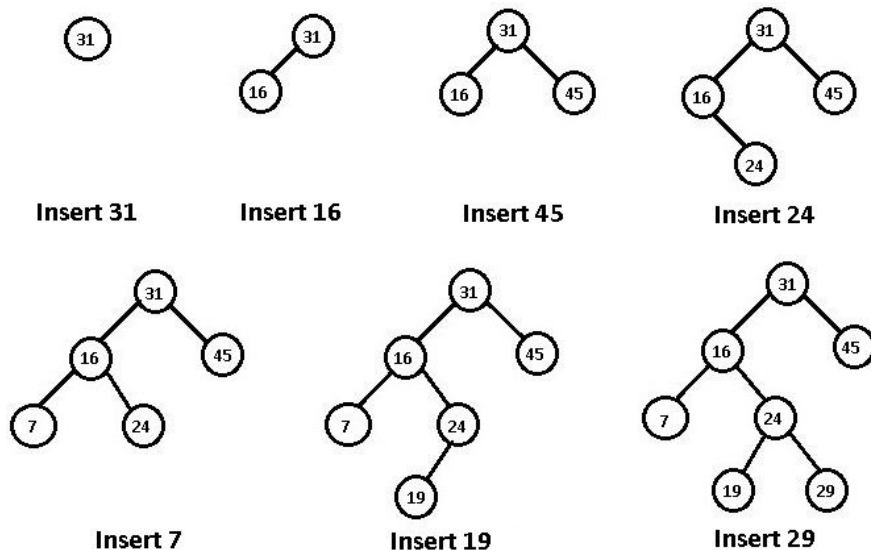
A binary tree + this magic... for every node:

left child is less than (<) node

right child is greater than (>) node

That's it. Let's build one. An empty BST is root = null (not shown below).

Below: the root is the first node added; in this case 31.



Source: [csegeek.com/csegeek/view/tutorials/algorithms/trees/tree\\_part2.php](http://csegeek.com/csegeek/view/tutorials/algorithms/trees/tree_part2.php)

Notice in our example:

- The root doesn't change when adding to the tree
- Every new node is added as a leaf

Performance for BST magic,

- Average performance is  $O(\log n)$ , problem cut in half with each subtree
- Worst-case performance is  $O(n)$ , unbalanced tree turns into a linked list (dop!)

There are 3 important methods in the BST ADT:

1. put( K key, V value) - we just did this
2. V get( K key)
3. V remove( K key)

See **Muganda Code 22-8, 22-9** for Java code.

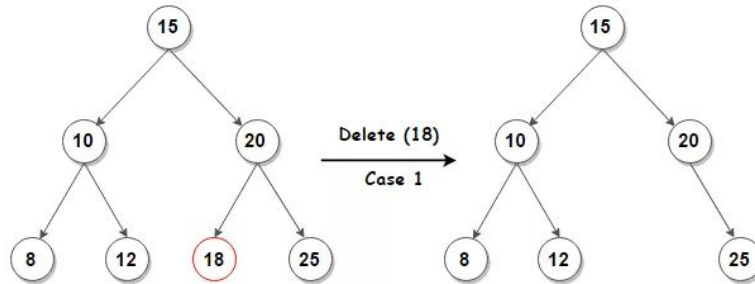
With **put()** - Often, we just show the keys. The value is there or it's just keys (like a set). Use same left/right algorithm as get() below. New node is always a leaf!

Here's **get()** pseudocode... it's a recursive search:

```
get( K key) {  
    return getNode( root, key)           // start at root  
}  
  
V getNode( Node n, K key) {  
    if n == null then return null        // NOT found  
  
    if key == node.key return node.value // FOUND  
  
    if key < node.key  
        return getNode( node.left, key) // look LEFT  
    else  
        return getNode( node.right, key) // look RIGHT  
}
```

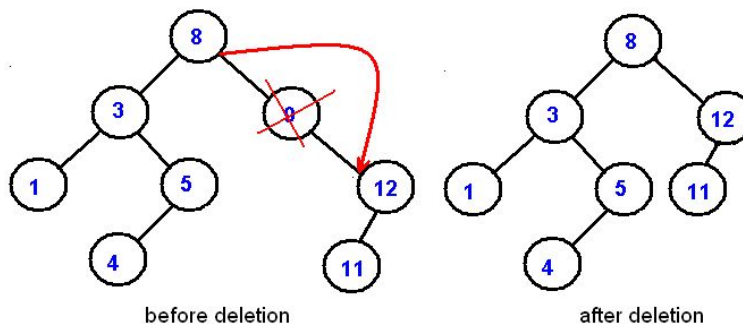
Remove is a little tougher.

Three cases, removing a node with no children (leaf), one child, and two children:  
 → No children (leaf) - null out the parent's link to the node (easy)



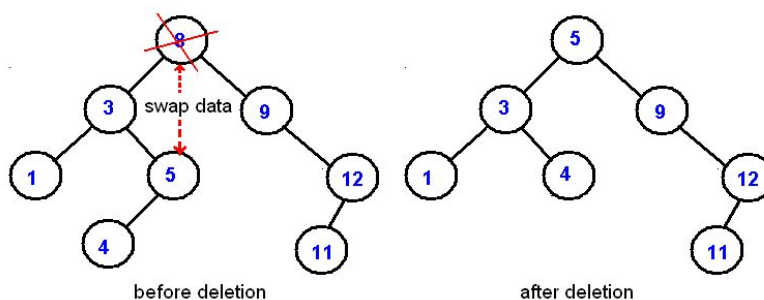
Source: [www.techiedelight.com/deletion-from-bst/](http://www.techiedelight.com/deletion-from-bst/)

→ One child - replace node with its child (pretty easy)



Source: [www.cs.cmu.edu/~adamchik/15-121/lectures/Trees/pix/del01.bmp](http://www.cs.cmu.edu/~adamchik/15-121/lectures/Trees/pix/del01.bmp)

→ Two children - replace node with predecessor (largest node in left subtree, tougher)



About two children - Successor is ok too, smallest node in right subtree; Pred/Succ are always a leaf or one-child node. Yes?

## B. Priority Queue

\*\* Book: **Muganda 22.4**

\*\* Online: great animation: [www.cs.usfca.edu/~galles/visualization/Heap.html](http://www.cs.usfca.edu/~galles/visualization/Heap.html)

### 22.4 Priority Queue

**Priority Queue ADT** - Insert based on a user-specified priority rather than order of insertion like a regular, old queue. Operations include:

```
insert( item)
item removeMin()
boolean isEmpty()
```

**Heap property** - each node is smaller than its children

Pseudocode:

```
// insert item into the heap
insert( item)
    add item as next leaf node
    while heap property is not met
        swap node with parent

// remove and return the smallest item from the heap
item removeMin()
    minItem = root
    put last leaf as root    // restore heap
    while heap property is not met
        swap node with smallest child
    return minItem
```

JCF **PriorityQueue** holds **Comparable** objects. You can use a **Comparator** as well. [docs.oracle.com/javase/8/docs/api/java/util/PriorityQueue.html](http://docs.oracle.com/javase/8/docs/api/java/util/PriorityQueue.html)

**Heapsort** - add items to heap, then removeMin() them for sorted order.

Terms: complete binary tree, binary tree depth

Heap performance:

- insert is  $O(\log n)$  because the tree depth is  $\log n$ .

- removeMin is  $O(\log n)$ ... the min is right there,  $O(1)$ , but you have to swap and restore the heap, which is  $O(\log n)$

BTW - PQ and Heap can be flipped to max if you like... parent greater than children and removeMax().

### Heap as an array

The BIG \$\$\$ for heap = removeMin() and storing the heap as an array

- works because it is a complete binary tree

The visualization shows you the array representation right next to the graphical tree.

[www.cs.usfca.edu/~galles/visualization/Heap.html](http://www.cs.usfca.edu/~galles/visualization/Heap.html)

Equations for array storage of a heap:

root of tree =  $A[0]$

parent of node  $A[k] = A[(k-1)/2]$

left child of node  $A[k] = A[2k+1]$

right child of node  $A[k] = A[2k + 2]$  // left child + 1